

# Continuous-variable quantum states designs: theory and applications

**Joseph T. Josue**, Kunal Sharma, Michael J. Gullans, Victor V. Albert

arXiv:2211.05127



*Quantum Information Processing (QIP)*  
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# Overview

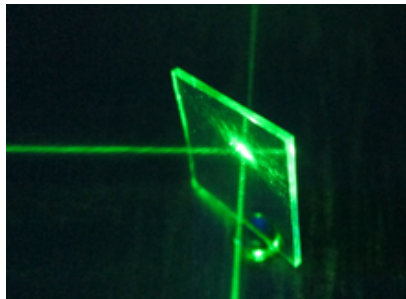
- 1 Motivation
- 2 Finite dimensions
- 3 Infinite dimensions
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# Use cases of infinite dimensions

- Continuous-variable systems are useful in technologies necessary for communication and computation
- Offers some advantages over finite-dimensional spaces
  - ▶ Continuous-parameter families of transversal gates (Eastin-Knill no-go in DV)
  - ▶ Hamiltonian-based bias-preserving gates (no-go in DV)
  - ▶ See review [V. V. Albert, arXiv:2211.05714](#)



# Rough discrete & continuous variable analogies

discrete (finite)	continuous (infinite)
qudit	oscillator
Pauli group generated by $\{X, Z\}$	displacements generated by $\{e^{i\hat{x}}, e^{i\hat{p}}\}$
stabilizer states	Gaussian states <i>Gross (2006)</i>
Clifford group	Gaussian operations
Pauli/Clifford channels	Gaussian channels
Pauli measurements	homodyne measurements
state tomography	Wigner function
stabilizer/Clifford $2^*$ -design	Gaussian states/operations <b>NOT</b> 2-design

\*: For prime dimensions, *Graydon et. al. (2021)*

Blume–Kohout,  
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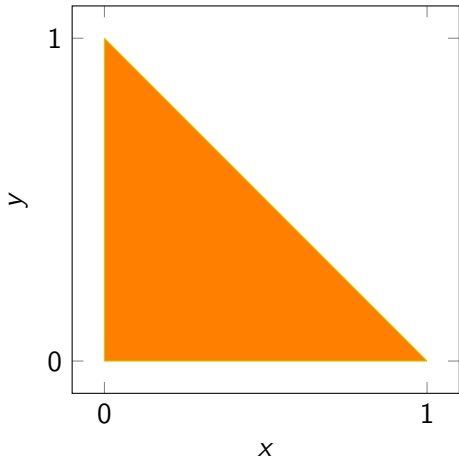
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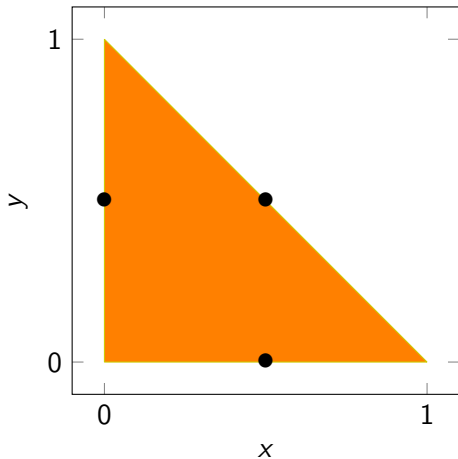
What is a  $t$ -design?  $\int_{\text{hard space}} (\deg t \text{ poly}) = \int_{\text{easier space}} (\deg t \text{ poly})$

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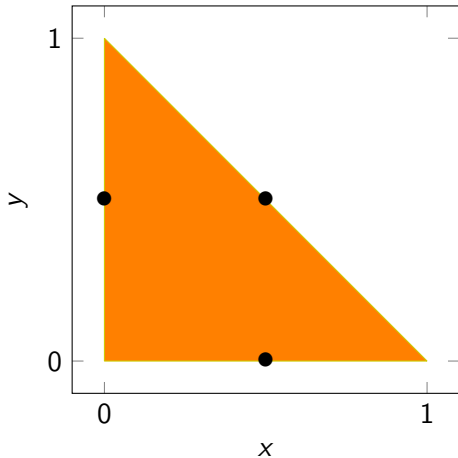
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$\mathcal{D}$  is a 2-design for  $X$

If  $g(x, y) = ax^2 + by^2 + cxy + dx + ey + f$ , then

$$\frac{1}{6} \sum_{(x,y) \in \mathcal{D}} g(x, y) = \int_X g(x, y) dx dy$$



# Why are designs interesting?

$$X = S^d$$

spherical design

$$X = U(d)$$

unitary design

$$X = \mathbb{CP}^{d-1}$$

qudit design

Numerical integration

$$X \subset \mathbb{R}^n$$

*e.g. Stroud 1971*

Error correction

$$X = S^d$$

*e.g. Delsarte, Goethals, Seidel 1977*

Randomized benchmarking

$$X = U(d)$$

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State tomography

$$X = \mathbb{CP}^{d-1}$$

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State distinction

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Shadow tomography

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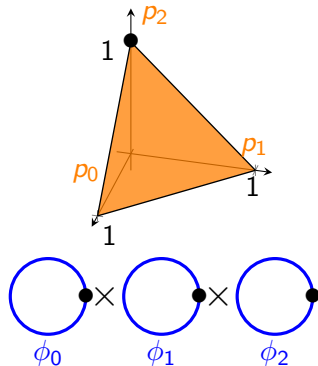
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# A useful characterization of quantum state designs

- Consider the parameterization

$$|p, \phi\rangle := \sum_{n=0}^{d-1} \sqrt{p_n} e^{i\phi_n} |n\rangle$$



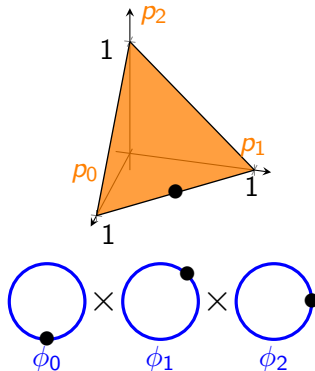
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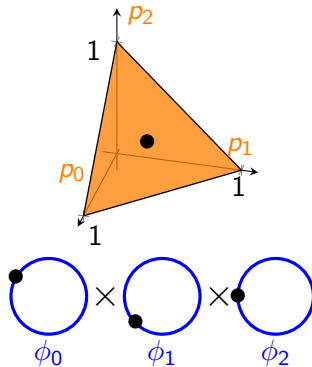


$$\sqrt{1/2} e^{i(-\pi/2)} |0\rangle + \sqrt{1/2} e^{i(\pi/4)} |1\rangle + \sqrt{0} e^{i(0)} |2\rangle$$

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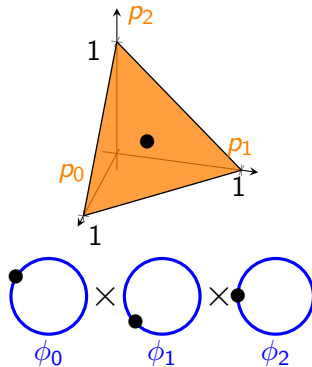
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## Theorem

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A simplex  $t$ -design and a torus  $t$ -design combine to yield a quantum state  $t$ -design.



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# Non-existence of continuous-variable designs

- For any  $t$ ,  $\mathbb{CP}^{d-1}$  and  $U(d)$   $t$ -designs exist
- For many dimensions, the Clifford group yields a unitary 2-design
- Gaussian unitaries (states) **do not** form a CV unitary (state) 2-design

Seymour,  
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## Theorem (Our work)

For any  $t \geq 2$ , continuous-variable state/unitary  $t$ -designs **do not** exist.

## Rough intuition for the no-go theorem

- In finite dimensions, a quantum state design yields a simplex design
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- Roughly, we show that any simplex ( $t \geq 2$ )-design requires a point “close to” the centroid (uniform probability distribution)  $(1/d, \dots, 1/d) \in \Delta^{d-1}$
- The centroid is ill-defined in the  $d \rightarrow \infty$  limit

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More formally, we use convergence theorems and the *Riesz Weak Compactness Theorem* to show that there does not exist a (signed or unsigned) abstract measure space satisfying the design conditions.



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# How do we get around the no-go theorem?

- Consider  $\mathcal{H} = L^2(\mathbb{R})$  with (Fock) basis  $\{|n\rangle \mid n \in \mathbb{N}_0\}$
- Allow ourselves to use non-normalizable states (e.g. homodyne quadrature eigenstates, GKP states, phase states)

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Example (Fock states plus phase states form a **rigged 2-design**)

$$\{|n\rangle\}_{n \in \mathbb{N}_0} \cup \left\{ |\theta_\varphi\rangle := \sum_{n \in \mathbb{N}_0} e^{i\theta n + i\varphi n^2} |n\rangle \right\}_{\theta, \varphi \in [-\pi, \pi)}$$

- Phase states give us the required non-normalizable centroids!

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“Rigged” is a reference to the rigged Hilbert space prescription that is used to formalize the construction

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## App. 1: Continuous-variable design-based shadow tomography

- Properties of designs ensure that a relatively small number of **qubit shadows** yield a good approximation of a state for estimating observable expectation value
- Our phase-state + Fock-state rigged 2-designs yield CV shadows with similar guarantees

$$S = \begin{cases} 3 |0/1\rangle\langle 0/1| - \mathbb{I} \\ 3 |\pm\rangle\langle \pm| - \mathbb{I} \\ 3 |\pm i\rangle\langle \pm i| - \mathbb{I} \end{cases} \quad \mathbb{E}_{S \in \text{shadows}} S = \text{state} \quad S = \begin{cases} (2\pi + 1) |\theta_\varphi\rangle\langle \theta_\varphi| - \mathbb{I} \\ (2\pi + 1) |n\rangle\langle n| - \mathbb{I} \end{cases}$$

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$$S = \begin{cases} (2\pi + 1)|\theta_\varphi\rangle\langle \theta_\varphi| - \mathbb{I} \\ (2\pi + 1)|n\rangle\langle n| - \mathbb{I} \end{cases}$$

Estimate  $\text{Tr}(\rho \mathcal{O}_j)$  for a collection  $i = j, \dots, M$

Rigged 3-design,  $N \sim \log(M) \max_j f(\mathcal{O}_j)$

Rigged 2-design,  $N \sim \log(M) \max_j g(\mathcal{O}_j, \rho)$

## App. 2: Regularized rigged designs

- Recall that a rigged  $t$ -design utilizes non-normalizable states (*i.e.* tempered distributions)
- Choose a *regularizer*  $R$  to normalize non-normalizable states while retaining important features of the design

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### Example (Hard energy cutoff)

$R$  projects onto a (finite-dimensional) low energy subspace of  $L^2(\mathbb{R})$ ; e.g.  $R = \sum_{n=0}^{d-1} |n\rangle\langle n|$

### Example (Soft energy cutoff)

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$$|\theta_\varphi\rangle \propto \sum_{n \in \mathbb{N}_0} e^{i\theta n + i\varphi n^2} |n\rangle \mapsto \frac{1}{\text{norm}} R |\theta_\varphi\rangle \propto \sum_{n \in \mathbb{N}_0} e^{-\beta n + i\theta n + i\varphi n^2} |n\rangle$$

## App. 2: Average to entanglement fidelity

$$\bar{F}(\mathcal{E}) = \mathbb{E}_{\psi \in D} \langle \psi | \mathcal{E}(|\psi\rangle\langle\psi|) | \psi \rangle \quad \text{average fidelity}$$

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- $D = \mathbb{CP}^{d-1}$  or equivalently  $D = 2$ -design
- $|\phi\rangle =$  maximally entangled state
- Beautiful relation [Horodecki<sup>3</sup> \(1999\)](#)

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- With  $d_R = (\text{Tr } R)^2 / \text{Tr } R^2$ ,

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When  $R = \sum_{n=0}^{d-1} |n\rangle\langle n|$ ,  $d_R = d$

When  $R = e^{-\beta \hat{H}}$ ,  $d_R = 2 \text{Tr}(\rho_\beta \hat{H}) + 1$  where  $\rho_\beta$  is the thermal state

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# Summary

- Continuous-variable (e.g. oscillator) state and unitary  $t$ -designs do not exist for any  $t \geq 2$
- The reason they do not exist is due to state normalization
- Remove normalization (*i.e.* go to *rigged Hilbert space*) to generate *rigged designs*



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- Remove normalization (*i.e.* go to *rigged Hilbert space*) to generate *rigged designs*
- Rigged designs are POVMs *plus a little extra* — allows for shadow tomography
- Regularized rigged designs apply soft-energy cutoff — allows for notions of average fidelity

## Future directions

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- Find regularized rigged unitary designs

### Definition (Regularized rigged unitary design)

Let  $\mathcal{E}$  be an ensemble of unitaries in  $U(L^2(\mathbb{R}))$ .  $\mathcal{E}$  is an  **$R$ -regularized rigged unitary  $t$ -design** if for *all* quantum states  $|\psi\rangle \in L^2(\mathbb{R})$ ,  $\mathcal{E} |\psi\rangle$  is an  $R$ -regularized rigged state  $t$ -design.

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- Extend other finite dimensional design-based techniques to infinite dimensions with rigged designs (e.g. benchmarking continuous-variable devices)

Thanks!



Kunal Sharma



Michael J. Gullans



Victor V. Albert

Additional slides



## Sketch of the no-go theorem for $t = 2$

- Projecting to the infinite-dimensional simplex, we find that if a CV 2-design exists, then there exists a  $\sigma$ -finite measure space  $(X, \Sigma, \mu)$  and a sequence  $(p_i)_{i \in \mathbb{N}_0}$  of measurable maps  $p_i: X \rightarrow [0, 1]$  satisfying
  - ▶  $\sum_{i \in \mathbb{N}_0} p_i(x) = 1$  for almost all  $x \in X$ , and
  - ▶  $\int_X p_a(x) p_b(x) d\mu(x) = \frac{1}{2}(1 + \delta_{ab})$  for any  $a, b \in \mathbb{N}_0$
- Riesz Weak Compactness Theorem: there exists a  $q$  such that for all  $h \in L^2(X)$ ,  
 $\lim_{a \rightarrow \infty} \int_X p_a h d\mu = \int_X q h d\mu$
- Lebesgue Dominated Convergence Theorem:  $\lim_{a \rightarrow \infty} \int_X p_a p_b p_c d\mu = 0$ ; implies that  $q = 0$  a.e.
- Therefore,  $\lim_{a \rightarrow \infty} \int_X p_a p_b d\mu = 0 \neq \lim_{a \rightarrow \infty} \frac{1}{2}(1 + \delta_{ab}) = \frac{1}{2}$

# Regularized rigged unitary design

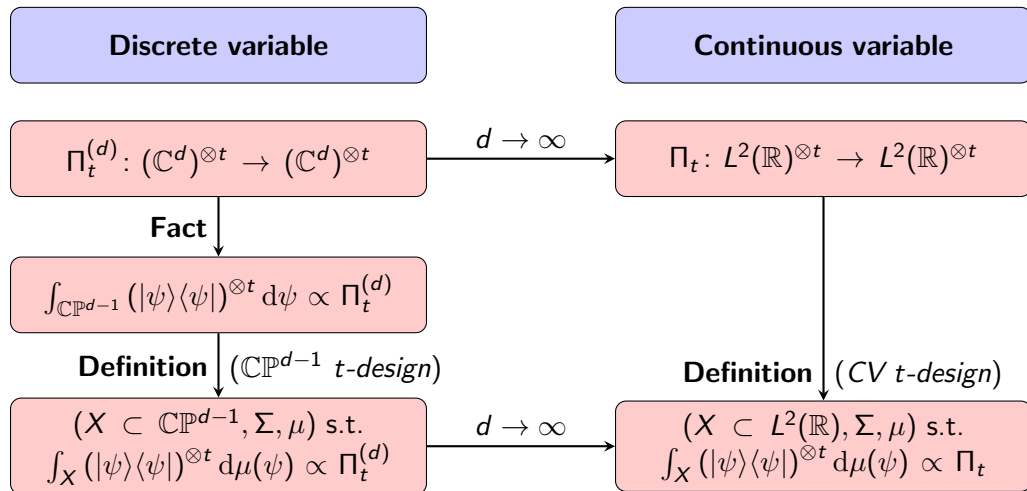
## Definition ( $U(d)$ $t$ -design)

Let  $\mathcal{E}$  be an ensemble of unitaries in  $U(d)$ .  $\mathcal{E}$  is a **unitary  $t$ -design** if for *all* quantum states  $|\psi\rangle \in \mathbb{CP}^{d-1}$ ,  $\mathcal{E} |\psi\rangle$  is a quantum state  $t$ -design.

## Definition (Regularized rigged unitary design)

Let  $\mathcal{E}$  be an ensemble of unitaries in  $U(L^2(\mathbb{R}))$ .  $\mathcal{E}$  is an  **$R$ -regularized rigged unitary  $t$ -design** if for *all* quantum states  $|\psi\rangle \in L^2(\mathbb{R})$ ,  $\mathcal{E} |\psi\rangle$  is an  $R$ -regularized rigged state  $t$ -design.

# Discrete to continuous-variable



# Continuous-variable to rigged

